



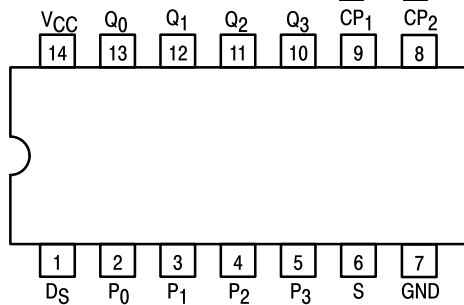
# 4-BIT SHIFT REGISTER

The SN54/74LS95B is a 4-Bit Shift Register with serial and parallel synchronous operating modes. The serial shift right and parallel load are activated by separate clock inputs which are selected by a mode control input. The data is transferred from the serial or parallel D inputs to the Q outputs synchronous with the HIGH to LOW transition of the appropriate clock input.

The LS95B is fabricated with the Schottky barrier diode process for high speed and is completely compatible with all Motorola TTL families.

- Synchronous, Expandable Shift Right
- Synchronous Shift Left Capability
- Synchronous Parallel Load
- Separate Shift and Load Clock Inputs
- Input Clamp Diodes Limit High Speed Termination Effects

**CONNECTION DIAGRAM DIP (TOP VIEW)**



NOTE:  
The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

V<sub>CC</sub> = PIN 14  
GND = PIN 7

**PIN NAMES**

S	Mode Control Input
D <sub>S</sub>	Serial Data Input
P <sub>0</sub> -P <sub>3</sub>	Parallel Data Inputs
CP <sub>1</sub>	Serial Clock (Active LOW Going Edge) Input
CP <sub>2</sub>	Parallel Clock (Active LOW Going Edge) Input
Q <sub>0</sub> -Q <sub>3</sub>	Parallel Outputs (Note b)

**LOADING (Note a)**

	HIGH	LOW
S	0.5 U.L.	0.25 U.L.
D <sub>S</sub>	0.5 U.L.	0.25 U.L.
P <sub>0</sub> -P <sub>3</sub>	0.5 U.L.	0.25 U.L.
CP <sub>1</sub>	0.5 U.L.	0.25 U.L.
CP <sub>2</sub>	0.5 U.L.	0.25 U.L.
Q <sub>0</sub> -Q <sub>3</sub>	10 U.L.	5 (2.5) U.L.

NOTES:

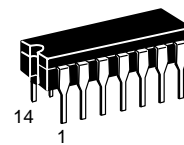
- a. 1 TTL Unit Load (U.L.) = 40 μA HIGH/1.6 mA LOW.  
 b. The Output LOW drive factor is 2.5 U.L. for Military (54) and 5 U.L. for Commercial (74) Temperature Ranges.

**GUARANTEED OPERATING RANGES**

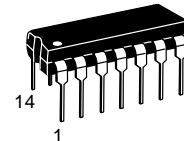
Symbol	Parameter		Min	Typ	Max	Unit
V <sub>CC</sub>	Supply Voltage	54 74	4.5 4.75	5.0 5.0	5.5 5.25	V
T <sub>A</sub>	Operating Ambient Temperature Range	54 74	-55 0	25 25	125 70	°C
I <sub>OH</sub>	Output Current — High	54, 74			-0.4	mA
I <sub>OL</sub>	Output Current — Low	54 74			4.0 8.0	mA

## SN54/74LS95B

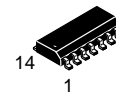
### 4-BIT SHIFT REGISTER LOW POWER SCHOTTKY



**J SUFFIX**  
CERAMIC  
CASE 632-08



**N SUFFIX**  
PLASTIC  
CASE 646-06



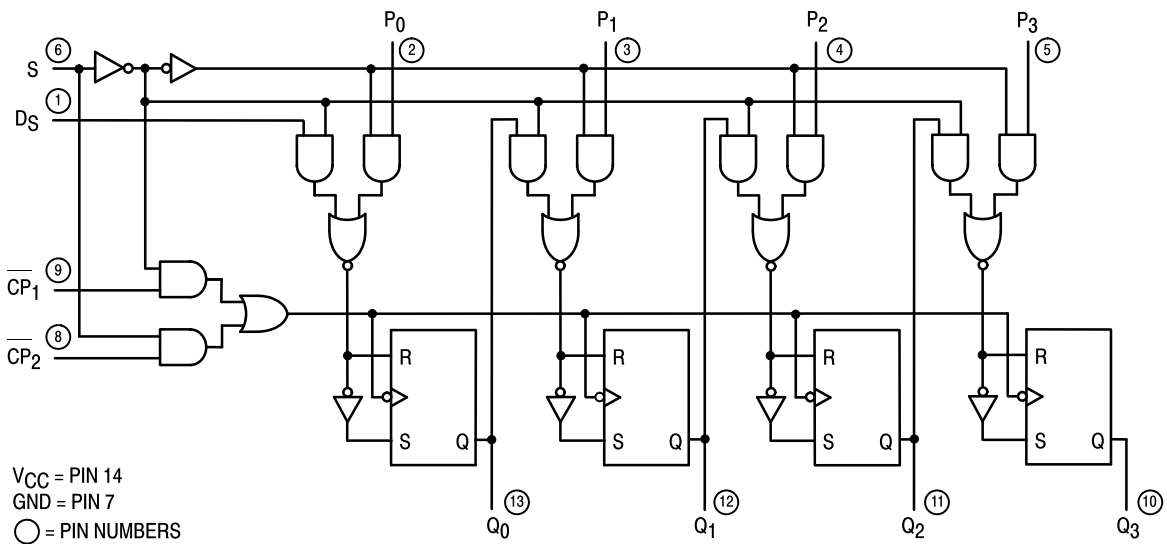
**D SUFFIX**  
SOIC  
CASE 751A-02

**ORDERING INFORMATION**

SN54LSXXJ	Ceramic
SN74LSXXN	Plastic
SN74LSXXD	SOIC

# SN54/74LS95B

## LOGIC DIAGRAM



## FUNCTIONAL DESCRIPTION

The LS95B is a 4-Bit Shift Register with serial and parallel synchronous operating modes. It has a Serial ( $D_S$ ) and four Parallel ( $P_0$ – $P_3$ ) Data inputs and four Parallel Data outputs ( $Q_0$ – $Q_3$ ). The serial or parallel mode of operation is controlled by a Mode Control input ( $S$ ) and two Clock Inputs ( $CP_1$ ) and ( $CP_2$ ). The serial (right-shift) or parallel data transfers occur synchronous with the HIGH to LOW transition of the selected clock input.

When the Mode Control input ( $S$ ) is HIGH,  $CP_2$  is enabled. A HIGH to LOW transition on enabled  $CP_2$  transfers parallel data from the  $P_0$ – $P_3$  inputs to the  $Q_0$ – $Q_3$  outputs.

When the Mode Control input ( $S$ ) is LOW,  $CP_1$  is enabled. A

HIGH to LOW transition on enabled  $CP_1$  transfers the data from Serial input ( $D_S$ ) to  $Q_0$  and shifts the data in  $Q_0$  to  $Q_1$ ,  $Q_1$  to  $Q_2$ , and  $Q_2$  to  $Q_3$  respectively (right-shift). A left-shift is accomplished by externally connecting  $Q_3$  to  $P_2$ ,  $Q_2$  to  $P_1$ , and  $Q_1$  to  $P_0$ , and operating the LS95B in the parallel mode ( $S = \text{HIGH}$ ).

For normal operation,  $S$  should only change states when both Clock inputs are LOW. However, changing  $S$  from LOW to HIGH while  $CP_2$  is HIGH, or changing  $S$  from HIGH to LOW while  $CP_1$  is HIGH and  $CP_2$  is LOW will not cause any changes on the register outputs.

MODE SELECT — TRUTH TABLE

OPERATING MODE	INPUTS					OUTPUTS			
	S	CP <sub>1</sub>	CP <sub>2</sub>	D <sub>S</sub>	P <sub>n</sub>	Q <sub>0</sub>	Q <sub>1</sub>	Q <sub>2</sub>	Q <sub>3</sub>
Shift	L	$\bar{L}$	X	l	X	L	q <sub>0</sub>	q <sub>1</sub>	q <sub>2</sub>
	L	$\bar{L}$	X	h	X	H	q <sub>0</sub>	q <sub>1</sub>	q <sub>2</sub>
Parallel Load	H	X	$\bar{L}$	X	P <sub>n</sub>	P <sub>0</sub>	P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>
Mode Change	$\bar{L}$	L	L	X	X	No Change			
	$\bar{L}$	L	L	X	X	No Change			
	$\bar{L}$	H	L	X	X	No Change			
	$\bar{L}$	H	L	X	X	Undetermined			
	$\bar{L}$	L	H	X	X	Undetermined			
	$\bar{L}$	L	H	X	X	No Change			
	$\bar{L}$	H	H	X	X	Undetermined			
	$\bar{L}$	H	H	X	X	No Change			

L = LOW Voltage Level

H = HIGH Voltage Level

X = Don't Care

l = LOW Voltage Level one set-up time prior to the HIGH to LOW clock transition.

h = HIGH Voltage Level one set-up time prior to the HIGH to LOW clock transition.

P<sub>n</sub> = Lower case letters indicate the state of the referenced input (or output) one set-up time prior to the HIGH to LOW clock transition.

# SN54/74LS95B

## DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

Symbol	Parameter	Limits			Unit	Test Conditions	
		Min	Typ	Max			
V <sub>IH</sub>	Input HIGH Voltage	2.0			V	Guaranteed Input HIGH Voltage for All Inputs	
V <sub>IL</sub>	Input LOW Voltage	54		0.7	V	Guaranteed Input LOW Voltage for All Inputs	
		74		0.8			
V <sub>IK</sub>	Input Clamp Diode Voltage		-0.65	-1.5	V	V <sub>CC</sub> = MIN, I <sub>IN</sub> = -18 mA	
V <sub>OH</sub>	Output HIGH Voltage	54	2.5	3.5	V	V <sub>CC</sub> = MIN, I <sub>OH</sub> = MAX, V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> per Truth Table	
		74	2.7	3.5	V		
V <sub>OL</sub>	Output LOW Voltage	54, 74		0.25	0.4	V	I <sub>OL</sub> = 4.0 mA V <sub>CC</sub> = V <sub>CC</sub> MIN, V <sub>IN</sub> = V <sub>IL</sub> or V <sub>IH</sub> per Truth Table
		74		0.35	0.5	V	
I <sub>IH</sub>	Input HIGH Current			20	μA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7 V	
				0.1	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 7.0 V	
I <sub>IL</sub>	Input HIGH Current			-0.4	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 0.4 V	
I <sub>OS</sub>	Short Circuit Current (Note 1)	-20		-100	mA	V <sub>CC</sub> = MAX	
I <sub>CC</sub>	Power Supply Current			21	mA	V <sub>CC</sub> = MAX	

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.

## AC CHARACTERISTICS (T<sub>A</sub> = 25°C, V<sub>CC</sub> = 5.0 V)

Symbol	Parameter	Limits			Unit	Test Conditions
		Min	Typ	Max		
f <sub>MAX</sub>	Maximum Clock Frequency	25	36		MHz	V <sub>CC</sub> = 5.0 V C <sub>L</sub> = 15 pF
t <sub>PLH</sub> t <sub>PHL</sub>	CP to Output		18	27	ns	
			21	32	ns	

## AC SETUP REQUIREMENTS (T<sub>A</sub> = 25°C, V<sub>CC</sub> = 5.0 V)

Symbol	Parameter	Limits			Unit	Test Conditions
		Min	Typ	Max		
t <sub>W</sub>	CP Pulse Width	20			ns	V <sub>CC</sub> = 5.0 V
t <sub>s</sub>	Data Setup Time	20			ns	
t <sub>h</sub>	Data Hold Time	20			ns	
t <sub>s</sub>	Mode Control Setup Time	20			ns	
t <sub>h</sub>	Mode Control Hold Time	20			ns	

# SN54/74LS95B

## DESCRIPTION OF TERMS

SETUP TIME ( $t_s$ ) — is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from HIGH to LOW in order to be recognized and transferred to the outputs.

HOLD TIME ( $t_h$ ) — is defined as the minimum time following

the clock transition from HIGH to LOW that the logic level must be maintained at the input in order to ensure continued recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from HIGH to LOW and still be recognized.

## AC WAVEFORMS

The shaded areas indicate when the input is permitted to change for predictable output performance.

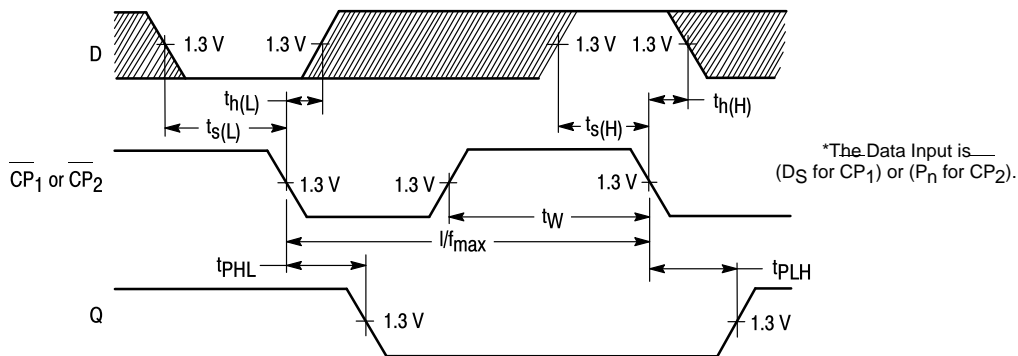


Figure 1

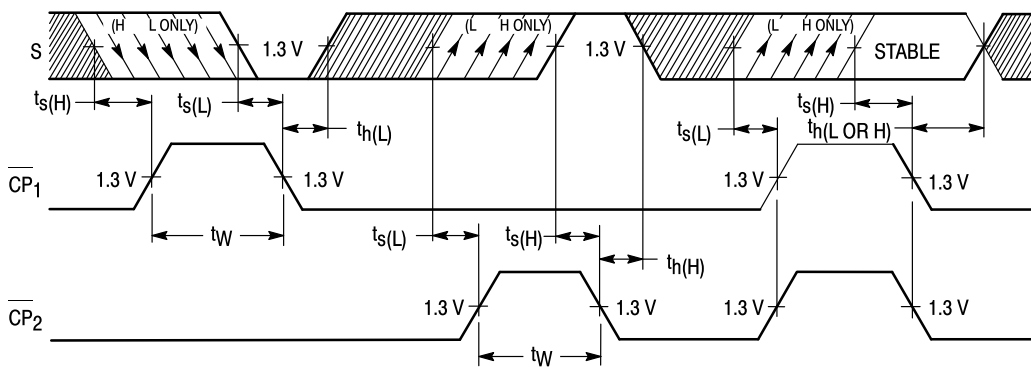
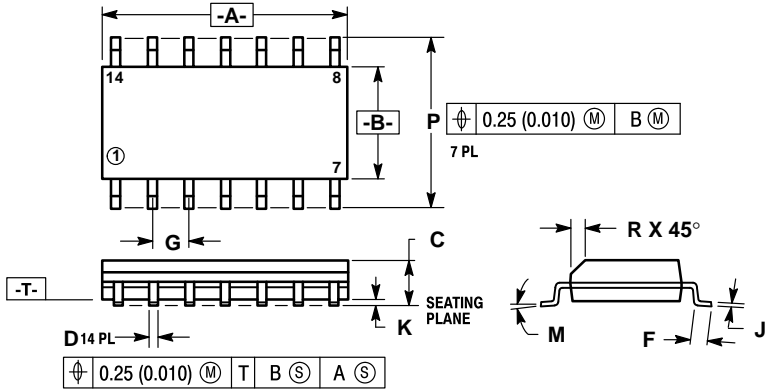


Figure 2

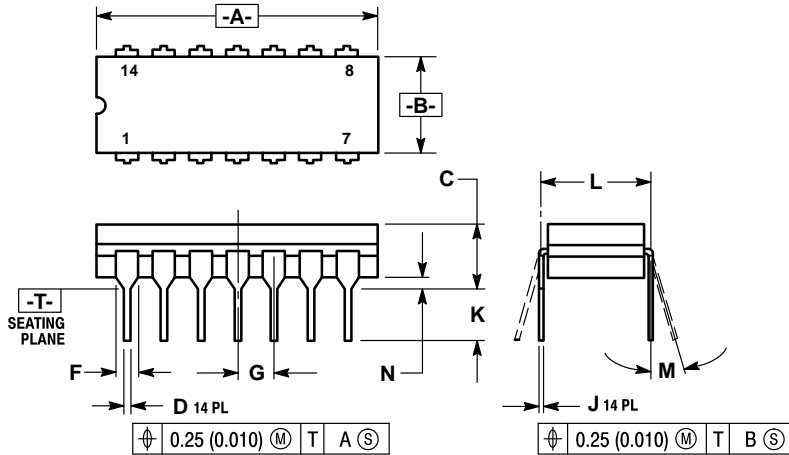
**Case 751A-02 D Suffix  
14-Pin Plastic  
SO-14**



- NOTES:
1. DIMENSIONS "A" AND "B" ARE DATUMS AND "T" IS A DATUM SURFACE.
  2. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  3. CONTROLLING DIMENSION: MILLIMETER.
  4. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
  5. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
  6. 751A-01 IS OBSOLETE, NEW STANDARD 751A-02.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	8.55	8.75	0.337	0.344
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

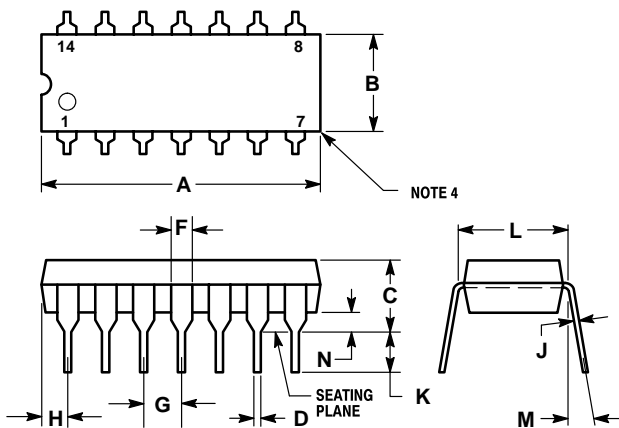
**Case 632-08 J Suffix  
14-Pin Ceramic Dual In-Line**



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
  4. DIM F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY.
  5. 632-01 THRU -07 OBSOLETE, NEW STANDARD 632-08.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	19.05	19.94	0.750	0.785
B	6.23	7.11	0.245	0.280
C	3.94	5.08	0.155	0.200
D	0.39	0.50	0.015	0.020
F	1.40	1.65	0.055	0.065
G	2.54 BSC		0.100 BSC	
J	0.21	0.38	0.008	0.015
K	3.18	4.31	0.125	0.170
L	7.62 BSC		0.300 BSC	
M	0°	15°	0°	15°
N	0.51	1.01	0.020	0.040

**Case 646-06 N Suffix  
14-Pin Plastic**



- NOTES:
1. LEADS WITHIN 0.13 mm (0.005) RADIUS OF TRUE POSITION AT SEATING PLANE AT MAXIMUM MATERIAL CONDITION.
  2. DIMENSION "L" TO CENTER OF LEADS WHEN FORMED PARALLEL.
  3. DIMENSION "B" DOES NOT INCLUDE MOLD FLASH.
  4. ROUNDED CORNERS OPTIONAL.
  5. 646-05 OBSOLETE, NEW STANDARD 646-06.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	18.16	19.56	0.715	0.770
B	6.10	6.60	0.240	0.260
C	3.69	4.69	0.145	0.185
D	0.38	0.53	0.015	0.021
F	1.02	1.78	0.040	0.070
G	2.54 BSC		0.100 BSC	
H	1.32	2.41	0.052	0.095
J	0.20	0.38	0.008	0.015
K	2.92	3.43	0.115	0.135
L	7.62 BSC		0.300 BSC	
M	0°	10°	0°	10°
N	0.39	1.01	0.015	0.039

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