

b/

A	10110
B	10111
C	1010
D	100
E	110
F	111
G	00
H	01

(Essentially)
Unique Huffman
Code

c/ The smallest average code length is the average code length for the Huffman code in 1b, namely

$$\begin{aligned}L_{\min} &= \frac{1}{64} (5 \times (2+3) + 4 \times 4 + 3 \times (6+10+12) + 2 \times (13+14)) \\ &= \frac{1}{64} (5 \times 5 + 4 \times 4 + 3 \times 28 + 2 \times 27) \\ &= \frac{1}{64} (25 + 16 + 84 + 54) \\ &= \frac{1}{64} (25 + 100 + 54) = \frac{179}{64}\end{aligned}$$

We have $H(p) \neq \frac{179}{64}$ because $p_i \neq 2^{-n_i}$ for some integer n_i

e.g. $p_c = 3 \times 2^{-6}$

#2

a/ Phrases

N	(binary)		
0	00000	λ	
1	00001	0	00000 0
2	00010	00	00001 0
3	00011	1	00000 1
4	00100	001	00010 1
5	00101	10	00011 0
6	00110	000	00010 0
7	00111	11	00011 1
8	01000	100	00101 0
9	01001	111	00111 1
10	01010	1000	01000 0
11	01011	110	00111 0
12	01100	0011	00100 1
13	01101	01	00001 1
14	01110	10001	01010 1
15	01111	1101	01011 1
16	10000	101	00101 1
17	10001	1100	01011 0

Bit stream generated
by LZ alg.
↓

∴ We parse in blocks of size 6 (5+1):

			\downarrow N \downarrow innovation bit	
1	00000	0	0 + 0	0
2	00001	0	1 + 0	00
3	00000	1	0 + 1	1
4	00010	1	2 + 1	001
5	00011	0	3 + 0	10
6	00010	0	2 + 0	000
7	00011	1	3 + 1	11
8	00101	0	5 + 0	100
9	00101	1	7 + 1	111
10	01000	0	8 + 0	1000
11	00111	0	7 + 0	110
12	01000	1	8 + 1	1001 ← ERROR
13	00001	1	1 + 1	01
14	01010	1	10 + 1	10001
15	01011	1	11 + 1	1101
16	00100	1	4 + 1	0011 ← ERROR
17	01011	0	11 + 0	1100

Decoder will not know that errors are present since the parsing does not yield any contradiction, i.e., point to entries in the dictionary not yet generated. Also, none of the codewords is duplicated!

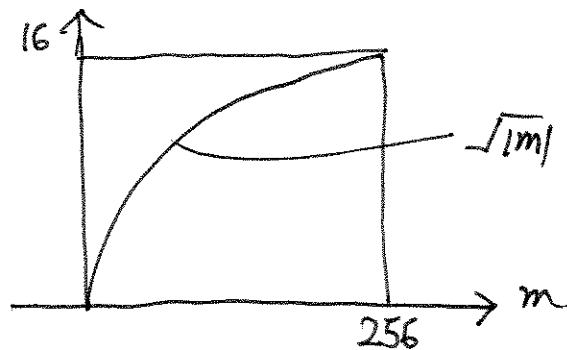
d We parse again

1	00000	0	0 + 0
2	00001	0	1 + 0
3	00000	1	0 + 1
4	00010	1	2 + 1
5	00011	0	3 + 0
6	00010	0	2 + 0
7	00011	1	3 + 1
8	00101	0	5 + 0
9	00111	1	7 + 1
10	11000	0	24 + 0
11	00111	0	7 + 0
12	01000	1	8 + 1
13	00001	1	1 + 1
14	01010	1	10 + 1
15	01011	1	11 + 1
16	00101	1	5 + 1
17	01011	0	11 + 0

← ERROR - Will be detected since entry $N=24$ has not been built yet!

#3

a/ Here $R=5$ so that $L=2^R=2^5=32$ - The uniform ^{quantizer} has 32 levels and operates on the interval $(-16, 16)$ (since $\sqrt{256} = 16$).



\therefore The cells C_1, \dots, C_L are simply

$(-16, -15), \dots, (-1, 0), (0, 1), \dots, (15, 16)$

with associated levels

$-15.5, -14.5, \dots, -0.5, 0.5, \dots, 14.5, 15.5$

b/ The cells $\tilde{C}_1, \dots, \tilde{C}_L$ are simply

$(-256, -225), \dots, (-9, -4), (-4, -1), (-1, 0), (0, 1), (1, 4), (4, 9), \dots, (225, 256)$

with associated values $\tilde{V}_1, \dots, \tilde{V}_L$

$-15.5, \dots, -0.5, 0.5, \dots, 14.5, 15.5$

\hookrightarrow the quantized version of $m=60$ is simply 7.5 since $7^2 < 60 < 8^2$.

⊆ If $v = \Phi(m)$, $|m| \leq 256$, then the expansion characteristic is

$$m = \Phi^{-1}(v) = \sqrt{v} \operatorname{sgn}(v), \quad v \in \mathbb{R}.$$

⊆ The use of Ψ , instead of Φ , means that the interval $(-256, 256)$ is now mapped into itself (instead of $(-16, 16)$). This yields a better representation of signals in PCM-like systems since "magnitude is preserved".

#4

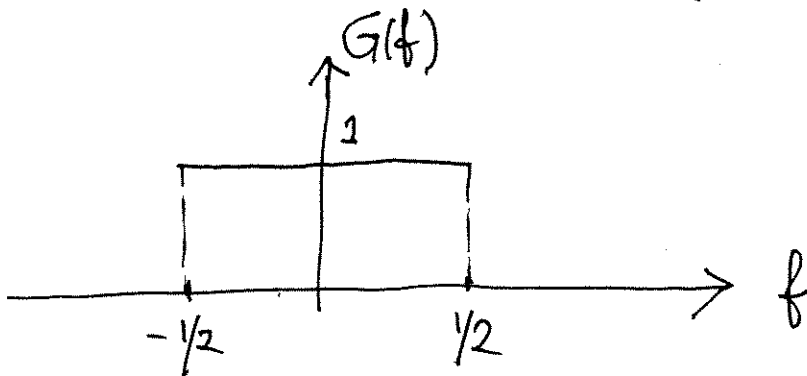
Q Since

$$\frac{\sin \pi t}{\pi t}$$



rectangular pulse

$$\begin{cases} 1 & \text{if } |t| \leq \frac{1}{2} \\ 0 & \text{if } |t| > \frac{1}{2} \end{cases}$$



The signal g is band-limited with cutoff $W = \frac{1}{2}$ so that
 $f^* = 2 \cdot \frac{1}{2} = 1$.

b) Here

$$g_{\text{PAM}}(t) = (g_{\delta} * p)(t), \quad t \in \mathbb{R}$$

so that

$$\begin{aligned} G_{\text{PAM}}(f) &= G_{\delta}(f) P(f) \\ &= f_s \sum_k G(f - kf_s) \cdot P(f), \quad f \in \mathbb{R} \end{aligned}$$

with $f_s = \frac{1}{T_s}$ and

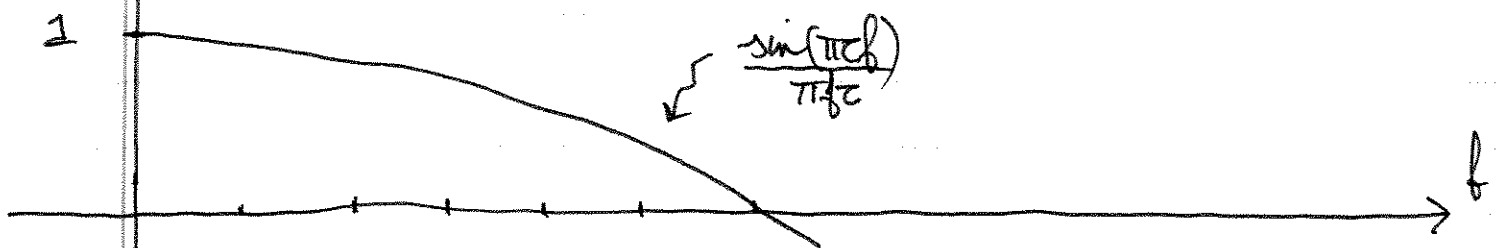
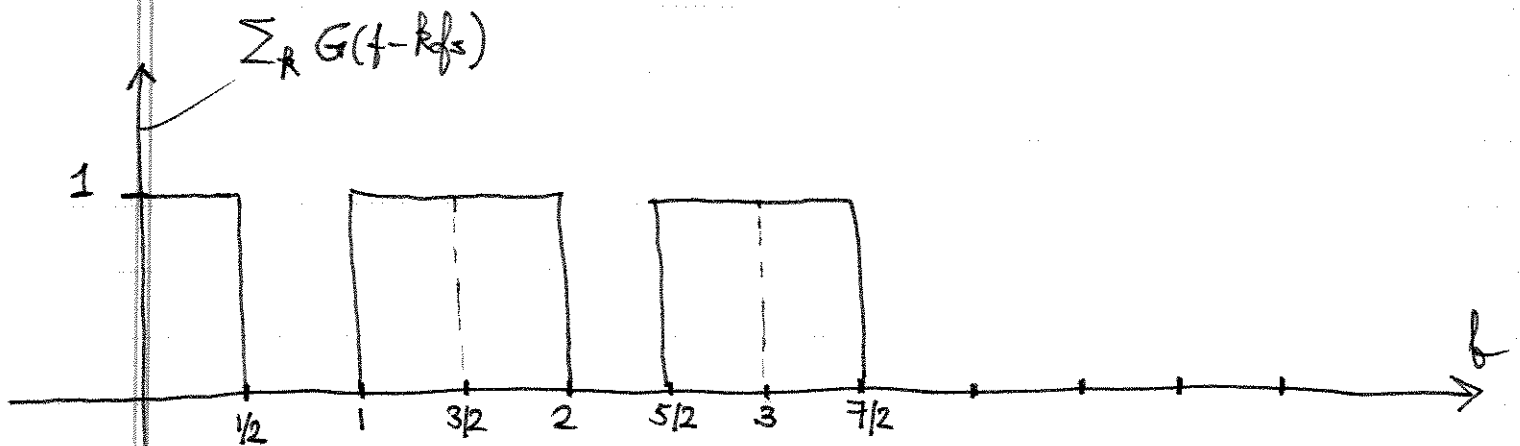
$$\begin{aligned} P(f) &= \int_0^{\tau} e^{-j2\pi ft} dt \\ &= \frac{e^{-j2\pi f\tau} - 1}{-j2\pi f} \\ &= \frac{e^{j\pi f\tau} - e^{-j\pi f\tau}}{2j\pi f} e^{-j\pi f\tau} \\ &= \frac{\sin(\pi f\tau)}{\pi f} e^{-j\pi f\tau}, \quad f \in \mathbb{R}. \end{aligned}$$

$$\therefore G_{\text{PAM}}(f) = f_s \left[\sum_k G(f - kf_s) \right] \frac{\sin(\pi f\tau)}{\pi f} e^{-j\pi f\tau}, \quad f \in \mathbb{R}$$

$$\therefore |G_{\text{PAM}}(f)| = T_s \left[\sum_k G(f - kf_s) \right] \left| \frac{\sin(\pi f T_s)}{\pi f T_s} \right|, \quad f \in \mathbb{R}.$$

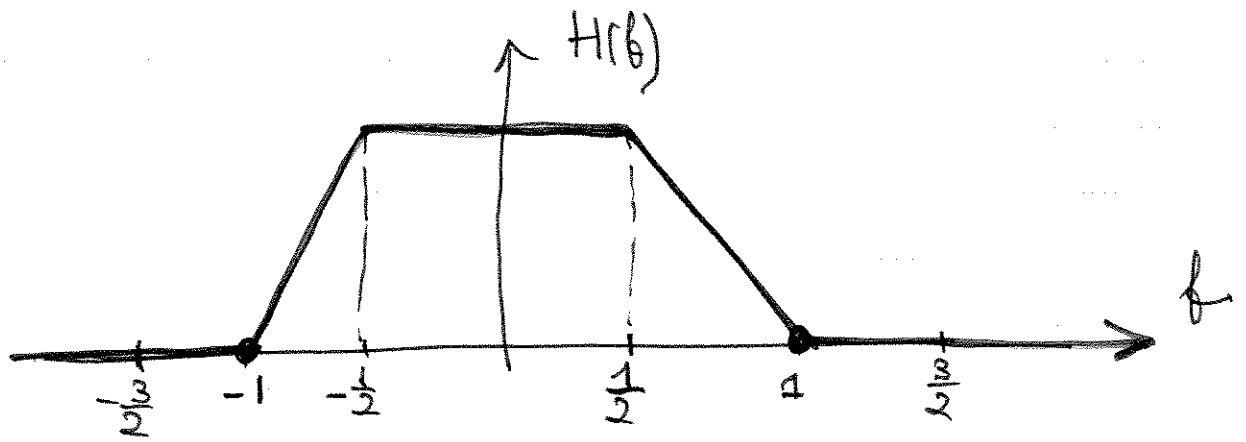
Here $T_s = \frac{2}{3} \Rightarrow f_s = \frac{3}{2}$

$\tau = \frac{1}{3} \Rightarrow \sin(\pi f \tau) = 0 \quad @ \quad \hat{f} = \frac{1}{\tau} = 3$



$$\tau f_s = \frac{1}{3} \cdot \frac{3}{2} = \frac{1}{2}$$

c/ Use the LP filter $H(f)$ given by



The maximum amplitude distortion occurs at $f = \frac{1}{2}$ and is equal to

$$\tau f_s \cdot \left| \frac{\sin(\pi f \tau)}{\pi f \tau} \right|$$

$$= \frac{1}{2} \frac{\sin(\pi/6)}{\pi/6}$$

$$= 3 \frac{\sin(\pi/6)}{\pi}$$

$$= \frac{3}{\pi} \cdot \frac{1}{2} = \frac{3}{2\pi} \#.$$