

**ENEE 621
SPRING 2016
ESTIMATION AND DETECTION THEORY**

ANSWER KEY TO TEST # 2:

- 1.** _____
1.a. Consider a Borel mapping $\psi : \mathbb{R} \rightarrow \mathbb{R}$ such that $\mathbb{E}_\theta [|\psi(Y)|] < \infty$ for each $\theta = 0, 1, \dots$
 – This condition is always satisfied since F_θ has finite support. The conditions

$$\mathbb{E}_\theta [\psi(Y)] = 0, \quad \theta = 0, 1, \dots$$

read

$$\frac{1}{2\theta + 1} \sum_{y=-\theta}^{\theta} \psi(y) = 0, \quad \theta = 0, 1, \dots$$

or equivalently,

$$\sum_{y=-\theta}^{\theta} \psi(y) = 0, \quad \theta = 0, 1, \dots \tag{1.1}$$

It follows that $\psi(0) = 0$ [Just take $\theta = 0$ above]. With $\theta = 0, 1, \dots$, use (1.1) with θ and $\theta + 1$ to conclude that

$$\psi(-(\theta + 1)) + \psi(\theta + 1) = 0.$$

The family $\{F_\theta, \theta = 0, 1, \dots\}$ is therefore *not* complete – Just take $\psi(y) = y$ (as expected!)

- 1.b.** There are several ways to show that the statistic $T : \mathbb{R} \rightarrow \mathbb{R}$ is sufficient.

_____ It suffices to note that

$$\mathbb{P}_\theta [Y = y] = h(\theta; T(y))q(y), \quad \begin{array}{l} y = 0, \pm 1, \dots \\ \theta = 0, 1, \dots \end{array}$$

with

$$h(t; \theta) = \mathbf{1}[t \leq \theta] \cdot \frac{1}{2\theta + 1}, \quad \begin{array}{l} t = 0, 1, \dots \\ \theta = 0, 1, \dots \end{array}$$

and

$$q(y) = 1, \quad y = 0, \pm 1, \dots$$

The sufficiency of the statistic $T : \mathbb{R} \rightarrow \mathbb{R}$ follows by the Factorization Theorem.

A direct calculation proceeds as follows: Fix $\theta = 0, 1, \dots$. With $t = 0$ and $y = 0, \pm 1, \dots$, we have

$$\mathbb{P}_\theta [T(Y) = 0] = \mathbb{P}_\theta [Y = 0] = \frac{1}{2\theta + 1}$$

and

$$\begin{aligned} \mathbb{P}_\theta [Y = y|T(Y) = 0] &= \frac{\mathbb{P}_\theta [Y = y, T(Y) = 0]}{\mathbb{P}_\theta [T(Y) = 0]} \\ &= \delta(0, y) \cdot \frac{\mathbb{P}_\theta [Y = 0]}{\mathbb{P}_\theta [T(Y) = 0]} \\ &= \delta(0, y). \end{aligned} \tag{1.2}$$

It is obvious that

$$\mathbb{P}_\theta [Y \in B|T(Y) = 0] = \mathbf{1}[0 \in B], \quad B \in \mathcal{B}(\mathbb{R})$$

regardless of θ and it is appropriate to take

$$\gamma(B; 0) = \mathbf{1}[0 \in B], \quad B \in \mathcal{B}(\mathbb{R}).$$

On the other hand, with $t = 1, 2, \dots, \theta$, and $y = \pm 1, \pm 2, \dots$, it holds that

$$\mathbb{P}_\theta [T(Y) = t] = \mathbb{P}_\theta [Y = t] + \mathbb{P}_\theta [Y = -t] = \frac{2}{2\theta + 1}$$

while

$$\begin{aligned} \mathbb{P}_\theta [Y = y|T(Y) = t] &= \frac{\mathbb{P}_\theta [Y = y, T(Y) = t]}{\mathbb{P}_\theta [T(Y) = t]} \\ &= \delta(t; |y|) \cdot \frac{\mathbb{P}_\theta [Y = y]}{\mathbb{P}_\theta [T(Y) = t]} \\ &= \delta(t; |y|) \cdot \frac{\frac{1}{2}}{\frac{2\theta+1}{2}} \\ &= \frac{1}{2} \cdot \delta(t; |y|). \end{aligned} \tag{1.3}$$

In conclusion, for $t = 1, \dots, \theta$, the conditional distribution of Y given $T(Y) = t$ under \mathbb{P}_θ is the uniform distribution on the set $\{-t, t\}$. As customary, this conditional distribution for all other values of t (i.e., those not in the support $\{0, 1, \dots, \theta\}$ of $T(Y)$) can be selected arbitrarily. Here we select it also to be the uniform distribution on the set $\{-t, t\}$. Therefore, in establishing that $T : \mathbb{R} \rightarrow \mathbb{R}$ is a sufficient statistic, it is appropriate to take

$$\gamma(B; t) = \frac{1}{2}\mathbf{1}[-t \in B] + \frac{1}{2}\mathbf{1}[t \in B], \quad \begin{array}{l} B \in \mathcal{B}(\mathbb{R}) \\ t \neq 0. \end{array}$$

1.c. Consider a Borel mapping $\psi : \mathbb{R} \rightarrow \mathbb{R}$ such that $\mathbb{E}_\theta [|\psi(T(Y))|] < \infty$ for each $\theta = 0, 1, \dots$. – This condition is always satisfied since F_θ has finite support. The conditions

$$\mathbb{E}_\theta [\psi(T(Y))] = 0, \quad \theta = 0, 1, \dots$$

read

$$\frac{1}{2\theta + 1} \sum_{y=-\theta}^{\theta} \psi(|y|) = 0, \quad \theta = 0, 1, \dots$$

or equivalently,

$$\psi(0) + 2 \sum_{y=1}^{\theta} \psi(y) = 0, \quad \theta = 0, 1, \dots \quad (1.4)$$

Taking $\theta = 0$ in (1.4) we obtain $\psi(0) = 0$, and (1.4) becomes

$$\sum_{y=1}^{\theta} \psi(y) = 0, \quad \theta = 0, 1, \dots \quad (1.5)$$

It is now plain that

$$\psi(y) = 0, \quad y = 0, 1, 2, \dots$$

so that

$$\mathbb{P}_{\theta} [\psi(|Y|) = 0] = 1, \quad \theta = 0, 1, \dots$$

The statistic $T : \mathbb{R} \rightarrow \mathbb{R}$ is indeed a complete sufficient statistic for the family $\{F_{\theta}, \theta = 0, 1, \dots\}$.

1.d. A Borel mapping $g : \mathbb{R} \rightarrow \mathbb{R}$ is an unbiased estimator if $\mathbb{E}_{\theta} [|g(Y)|] < \infty$ for every $\theta = 0, 1, \dots$ – This condition is always satisfied since F_{θ} has finite support, and

$$\mathbb{E}_{\theta} [g(Y)] = \theta, \quad \theta = 0, 1, \dots$$

This last condition is equivalent to

$$\sum_{y=-\theta}^{\theta} g(y) = \theta(2\theta + 1), \quad \theta = 0, 1, \dots \quad (1.6)$$

Take $\theta = 0$ in (1.6) to obtain $g(0) = 0$, and (1.6) now becomes

$$g(0) = 0, \quad \sum_{y=1}^{\theta} (g(-y) + g(y)) = \theta(2\theta + 1), \quad \theta = 1, 2, \dots \quad (1.7)$$

It follows that

$$g(-\theta) + g(\theta) = \theta(2\theta + 1) - (\theta - 1)(2\theta - 1), \quad \theta = 1, 2, \dots$$

and combining we get

$$g(0) = 0, \quad g(-y) + g(y) = 4y - 1, \quad y = 1, 2, \dots$$

1.e. For every $\theta = 0, 1, \dots$, note that

$$\begin{aligned} \widehat{g}(t) &= \mathbb{E}_{\theta} [g(Y) | T(Y) = t] \\ &= \begin{cases} g(0) & \text{if } t = 0 \\ \frac{1}{2} (g(-t) + g(t)) & \text{if } t = 1, 2, \dots \end{cases} \end{aligned} \quad (1.8)$$

with the adopted selection of $\gamma : \mathcal{B}(\mathbb{R}) \times \mathbb{R} \rightarrow [0, 1]$.

1.f. Finally, if $g : \mathbb{R} \rightarrow \mathbb{R}$ is an unbiased estimator, then by the Rao-Blackwell Theorem the estimator $\widehat{g} \circ T : \mathbb{R} \rightarrow \mathbb{R}$ is also an unbiased estimator with $\widehat{g} : \mathbb{R} \rightarrow \mathbb{R}$ given by

$$\widehat{g}(t) = \begin{cases} g(0) & \text{if } t = 0 \\ \frac{1}{2}(g(-t) + g(t)) & \text{if } t \neq 0. \end{cases} \quad (1.9)$$

But by Part **d**, the lack of bias for the estimator $g : \mathbb{R} \rightarrow \mathbb{R}$ requires that the conditions

$$g(0) = 0, \quad g(-t) + g(t) = 4t - 1, \quad t = 1, 2, \dots$$

hold, in which case

$$\widehat{g}(t) = \begin{cases} 0 & \text{if } t = 0 \\ \frac{1}{2}(4t - 1) & \text{if } t \neq 0. \end{cases} \quad (1.10)$$

The estimator $\widehat{g} \circ T : \mathbb{R} \rightarrow \mathbb{R}$ is therefore MVUE. Concretely,

$$(\widehat{g} \circ T)(y) = \begin{cases} 0 & \text{if } y = 0 \\ \frac{1}{2}(4|y| - 1) & \text{if } y \neq 0. \end{cases}$$

It is essentially the only MVUE as a consequence of the complete sufficiency of the statistics $T : \mathbb{R} \rightarrow \mathbb{R}$. For the particular situation at hand, it is also a direct consequence of Parts **d** and **e**.

2.

2.a. With the usual notation, for each $y = 0, 1, \dots$, we have

$$\begin{aligned} f_{\vartheta|Y}(t|y) &= \frac{\mathbb{P}[Y = y|\vartheta = t] f_{\vartheta}(t)}{\mathbb{P}[Y = y]} \\ &= \frac{(1-t)t^y(r+1)t^r}{\mathbb{P}[Y = y]} \\ &= \frac{(r+1)(1-t)t^{r+y}}{\mathbb{P}[Y = y]}, \quad 0 \leq t \leq 1 \end{aligned} \quad (1.11)$$

with

$$\begin{aligned} \mathbb{P}[Y = y] &= \int_0^1 (1-t)t^y(r+1)t^r dt \\ &= \frac{r+1}{r+y+1} - \frac{r+1}{r+y+2} \\ &= \frac{r+1}{(r+y+1)(r+y+2)}. \end{aligned} \quad (1.12)$$

Combining, we conclude that

$$\begin{aligned}
 f_{\vartheta|Y}(t|y) &= \frac{(r+1)(1-t)t^{r+y}}{\mathbb{P}[Y=y]} \\
 &= (r+1)(1-t)t^{r+y} \cdot \frac{(r+y+1)(r+y+2)}{r+1} \\
 &= (r+y+1)(r+y+2)(1-t)t^{r+y}
 \end{aligned} \tag{1.13}$$

on the range $0 < t < 1$.

2.b. Fix $y = 0, 1, \dots$. With $0 < t < 1$, we note that

$$\log f_{\vartheta|Y}(t|y) = \log(r+y+1)(r+y+2) + \log(1-t) + (r+y)\log t$$

so that

$$\frac{\partial}{\partial t} \log f_{\vartheta|Y}(t|y) = -\frac{1}{1-t} + (r+y)\frac{1}{t}.$$

The solution to the MAP equation

$$\frac{\partial}{\partial t} \log f_{\vartheta|Y}(t|y) = 0$$

is $\frac{r+y}{r+y+1}$, and the MAP estimator $g_{\text{MAP}} : \mathbb{R} \rightarrow \mathbb{R}$ can be defined by

$$g_{\text{MAP}}(y) = \frac{r+y^+}{r+y^++1}, \quad y \in \mathbb{R}.$$

Here (and elsewhere in this problem) we use y^+ (instead of y) to have an expression that is well defined on the *entirety* of \mathbb{R} rather than on \mathbb{N} since we have defined estimators as Borel mappings $\mathbb{R}^k \rightarrow \mathbb{R}^p$. This creates no contradiction with the alternate definition of the MAP estimator (found in many textbooks) as a mapping $g_{\text{MAP}} : \mathbb{N} \rightarrow \mathbb{R}$ given by

$$g_{\text{MAP}}(y) = \frac{r+y}{r+y+1}, \quad y = 0, 1, \dots$$

because the rv Y has its support on \mathbb{N} .

2.c. Fix $y = 0, 1, \dots$. We have

$$\begin{aligned}
 \mathbb{E}[\vartheta|Y=y] &= \int_0^1 t f_{\vartheta|Y}(t|y) dt \\
 &= \int_0^1 t(r+y+1)(r+y+2)(1-t)t^{r+y} dt \\
 &= (r+y+1)(r+y+2) \int_0^1 (1-t)t^{r+y+1} dt \\
 &= (r+y+1)(r+y+2) \left(\frac{1}{r+y+2} - \frac{1}{r+y+3} \right) \\
 &= (r+y+1)(r+y+2) \cdot \frac{1}{(r+y+2)(r+y+3)} \\
 &= \frac{r+y+1}{r+y+3}.
 \end{aligned} \tag{1.14}$$

and the MMSE estimator $g_{\text{MMSE}} : \mathbb{R} \rightarrow \mathbb{R}$ can be defined by

$$g_{\text{MMSE}}(y) = \frac{r + y^+ + 1}{r + y^+ + 3}, \quad y \in \mathbb{R}.$$

2.d. The ML estimator reduces to the MAP estimator when ϑ is uniformly distributed on $[0, 1]$; this corresponds to $r = 0$. Hence

$$g_{\text{ML}}(y) = \frac{y^+}{y^+ + 1}, \quad y \in \mathbb{R}.$$

Direct calculations are also possible.

3.

3.a. For each $\theta > 0$, the distribution F_θ admits a probability density function with respect to Lebesgue measure given by

$$f_\theta(y) = \theta h(y) H(y)^{\theta-1}, \quad y \in \mathbb{R}.$$

Therefore, for each $n = 1, 2, \dots$, the probability distribution $F_\theta^{(n)}$ also admits a probability density function with respect to Lebesgue measure given by

$$\begin{aligned} f_\theta^{(n)}(y_1, \dots, y_n) &= \prod_{i=1}^n f_\theta(y_i) \\ &= \theta^n \left(\prod_{i=1}^n h(y_i) H(y_i)^{\theta-1} \right) \\ &= \left(\prod_{i=1}^n h(y_i) \right) \cdot e^{n \log \theta + (\theta-1) \sum_{i=1}^n \log H(y_i)}, \quad \begin{array}{l} y_i \in \mathbb{R} \\ i = 1, \dots, n. \end{array} \end{aligned} \quad (1.15)$$

The condition $h(y) > 0$ for each y in \mathbb{R} implies

$$0 < H(y) = \int_{-\infty}^y h(t) dt < 1, \quad y \in \mathbb{R}.$$

The family $\{F_\theta^{(n)}, \theta > 0\}$ is an exponential family with

$$C(\theta) = \theta^n \quad \text{and} \quad Q(\theta) = \theta - 1, \quad \theta > 0$$

and

$$q(y_1, \dots, y_n) = \prod_{i=1}^n h(y_i) \quad \text{and} \quad K(y_1, \dots, y_n) = \sum_{i=1}^n \log H(y_i), \quad \begin{array}{l} y_i \in \mathbb{R} \\ i = 1, \dots, n. \end{array}$$

3.b. As well known, if Y is distributed according to F_θ , then the rv $F_\theta(Y)$ is uniformly distributed on $(0, 1)$. Here, $H(Y)^\theta = F_\theta(Y)$, hence the result $H(Y)^\theta \stackrel{st}{=} U$ where U is uniformly distributed on $(0, 1)$ under \mathbb{P}_θ . For each $p > 0$ we conclude that

$$\mathbb{E}_\theta [(\log H(Y))^p] = \theta^{-p} \mathbb{E}_\theta [(\log H(Y)^\theta)^p] = \theta^{-p} \mathbb{E}_\theta [(\log U)^p].$$

It follows that $\mathbb{E}_\theta [\log H(Y)] = -\theta^{-1}$ and $\mathbb{E}_\theta [(\log H(Y))^2] = 2\theta^{-2}$.

3.c. Fix $n = 1, 2, \dots$ and $\theta > 0$. Since

$$\log f_\theta(y) = \log \theta + \log h(y) + (\theta - 1) \log H(y), \quad \begin{array}{l} y \in \mathbb{R} \\ \theta > 0, \end{array}$$

we conclude that

$$\frac{\partial}{\partial \theta} \log f_\theta(y) = \frac{1}{\theta} + \log H(y), \quad \begin{array}{l} y \in \mathbb{R} \\ \theta > 0. \end{array}$$

Therefore,

$$\begin{aligned} \mathbb{E}_\theta \left[\left| \frac{\partial}{\partial \theta} \log f_\theta(Y) \right|^2 \right] &= \mathbb{E}_\theta \left[\left| \frac{1}{\theta} + \log H(Y) \right|^2 \right] \\ &= \mathbb{E}_\theta \left[\frac{1}{\theta^2} + \frac{2}{\theta} \log H(Y) + (\log H(Y))^2 \right] \\ &= \frac{1}{\theta^2} + \frac{2}{\theta} (\mathbb{E}_\theta [\log H(Y)]) + \mathbb{E}_\theta [(\log H(Y))^2] \\ &= \frac{1}{\theta^2} - \frac{2}{\theta^2} + \frac{2}{\theta^2} = \frac{1}{\theta^2} \end{aligned} \tag{1.16}$$

by the calculations carried in Part **b**. Thus,

$$M(\theta) = \theta^{-2}$$

and

$$M^{(n)}(\theta) = n\theta^{-2},$$

A simpler argument would proceed as follows: It is also the case here that

$$\frac{\partial^2}{\partial \theta^2} \log f_\theta(y) = -\frac{1}{\theta^2}, \quad \begin{array}{l} y \in \mathbb{R} \\ \theta > 0 \end{array}$$

and the desired conclusion immediately follows.

3.d. To find the ML estimator, given the observation y_1, \dots, y_n , consider the ML equation

$$\frac{\partial}{\partial \theta} \log f_\theta^{(n)}(y_1, \dots, y_n) = 0, \quad \theta > 0$$

or equivalently,

$$\sum_{i=1}^n \left(\frac{1}{\theta} + \log H(y_i) \right) = 0, \quad \theta > 0.$$

Its unique solution $g_{\text{ML}}(y_1, \dots, y_n)$ is given by

$$g_{\text{ML}}(y_1, \dots, y_n) = -\frac{n}{\sum_{i=1}^n \log H(y_i)}$$

with $g_{\text{ML}}(y_1, \dots, y_n) > 0$ as desired!

3.e. The ML estimator is strongly consistent (hence weakly consistent) since for each $\theta > 0$, the SLLNs implies

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \log H(Y_i) = \mathbb{E}_\theta [\log H(Y)] = -\theta^{-1} \quad \mathbb{P}_\theta - a.s.$$

so that

$$\lim_{n \rightarrow \infty} g_{\text{ML}}(Y_1, \dots, Y_n) = - \lim_{n \rightarrow \infty} \left(\frac{1}{n} \sum_{i=1}^n \log H(Y_i) \right)^{-1} = \theta \quad \mathbb{P}_\theta - a.s.$$

3.f. Finally, we get

$$\begin{aligned} \sqrt{n} (g_{\text{ML}}(Y_1, \dots, Y_n) - \theta) &= -\sqrt{n} \cdot \left(\frac{n}{\sum_{i=1}^n \log H(Y_i)} + \theta \right) \\ &= -\sqrt{n} \cdot \frac{n + \theta \sum_{i=1}^n \log H(Y_i)}{\sum_{i=1}^n \log H(Y_i)} \\ &= -\sqrt{n} \cdot \frac{1 + \theta \left(\frac{1}{n} \sum_{i=1}^n \log H(Y_i) \right)}{\frac{1}{n} \sum_{i=1}^n \log H(Y_i)} \\ &= -\sqrt{n} \cdot \frac{\frac{1}{n} \sum_{i=1}^n \log H(Y_i) - (-\theta^{-1})}{\frac{1}{n} \sum_{i=1}^n \log H(Y_i)} \cdot \theta \\ &= -\frac{\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n \log H(Y_i) - (-\theta^{-1}) \right)}{\frac{1}{n} \sum_{i=1}^n \log H(Y_i)} \cdot \theta \end{aligned}$$

The SLLNs for the rvs $\{\log H(Y_i), i = 1, 2, \dots\}$ (under \mathbb{P}_θ) yields

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \log H(Y_i) = -\theta^{-1} \quad \mathbb{P}_\theta - a.s.$$

whereas the corresponding CLT (under \mathbb{P}_θ) gives

$$\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n \log H(Y_i) - (-\theta^{-1}) \right) \Longrightarrow_n \sqrt{\text{Var}_\theta[\log H(Y)]} Z$$

where Z is a standard (zero-mean unit-variance) Gaussian rv. We have

$$\text{Var}_\theta[\log H(Y)] = \mathbb{E}_\theta [(\log H(Y))^2] - (\mathbb{E}_\theta [\log H(Y)])^2 = \frac{2}{\theta^2} - \frac{1}{\theta^2} = \frac{1}{\theta^2}.$$

Therefore,

$$\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n \log H(Y_i) - (-\theta^{-1}) \right) \Longrightarrow_n \theta^{-1} Z.$$

Combining these facts and using standard facts concerning convergence of rvs, we conclude that under \mathbb{P}_θ we have

$$\sqrt{n} (g_{\text{ML}}(Y_1, \dots, Y_n) - \theta) \Longrightarrow_n -\theta \cdot \left(\frac{\theta^{-1} Z}{-\theta^{-1}} \right) = \theta Z.$$

The limiting rv is indeed a Gaussian rv with zero mean and variance $\theta^2 = M(\theta)^{-1}$ (as expected).
