

Tuesday, November 2

1. Let $M(t_0, t_1)$ denote the observability Gramian

$$M(t_0, t_1) = \int_{t_0}^{t_1} \Phi^T(\sigma, t_0) C^T(\sigma) C(\sigma) \Phi(\sigma, t_0) d\sigma$$

where Φ denotes the transition matrix for the linear system

$$\dot{x}(t) = A(t)x(t) \quad ; \quad x(t_0) = x_0.$$

$$y(t) = C(t)x(t)$$

Show that

$$(a) \quad \frac{d}{dt} M(t, t_1) = -A^T(t)M(t, t_1) - M(t, t_1)A(t) - C^T(t)C(t)$$

$$M(t_1, t_1) = 0.$$

$$(b) \quad M(t_0, t_1) = M(t_0, t) + \Phi^T(t, t_0)M(t, t_1)\Phi(t, t_0)$$

2. Show controllability of $[A, B]$ is equivalent to

$$\text{rank} \begin{bmatrix} sI - A & B \end{bmatrix} = n$$

\nearrow
 $n \times (n+m)$ rectangular matrix

3 Consider the oscillator

$$\ddot{x}(t) + x(t) = 0.$$

Can $x(0)$ and $\dot{x}(0)$ be determined from knowledge of the value of $x(t)$ at $t = \pi, 2\pi, 3\pi, \dots$ etc.?

4. Consider a linear-time invariant system

$$\dot{x}(t) = A x(t)$$

$$y(t) = C x(t)$$

Suppose $y(t)$ is measured only at particular ~~instants~~ time instants, $t = 0, T, 2T, 3T, \dots$, for a suitable sampling time T . Determine conditions such that $x(0)$ can be determined uniquely from sufficiently many such samples.

[Hint: Consider a result analogous to that stated in problem 2.]