

$$\{x \in \mathbb{R}^n \mid V(x) \leq c\} = \Omega_c \subset B_r.$$

Thus  $\Omega_c$  is bounded, (and closed). By LaSalle's invariance principle  $x(t)$ , a trajectory beginning in  $\Omega_c$ ,  $\rightarrow M =$  largest invariant set  $\subset E = \{x \mid \dot{V} = 0\}$ , as  $t \rightarrow \infty$ .

By (iii)  $M = \{0\}$ .

Thus 0 is asymptotically ~~stability~~ stable and globally attractive.  $\square$

The idea of using "energy-like" functions can be used also to prove instability theorems. A fundamental result is due to Nikolai Guryevich Chetaev (1902-1959), a Soviet mechanician, who held the chair of Theoretical Mechanics at Moscow State University.

### Theorem (Chetaev)

Let  $x=0$  be an equilibrium point of  $\dot{x} = f(x)$ . Let  $V: D \rightarrow \mathbb{R}$  be a  $C^1$  function defined on an open, connected subset  $D$  of  $\mathbb{R}^n$  which contains 0, and such that  $\circ$

- (i)  $V(0) = 0$  and for every  $\varepsilon > 0$ , there exists  $x_0 \in B_\varepsilon(0)$  such that  $V(x_0) > 0$ .
- (ii) Let  $U = \{x \in B_r(0) \mid V(x) > 0\}$  for  $B_r \subset D$  and  $\dot{V}(x) \geq \phi(\|x\|) > 0$  on  $U$