

$$\leq \int_t^{t_0} \|f(\sigma, x(\sigma)) - f(\sigma, y(\sigma))\| d\sigma$$

$$\leq \int_t^{t_0} L \cdot \|x(\sigma) - y(\sigma)\| d\sigma$$

(by Lipschitz condition)

$$\leq L \cdot (t - t_0) \|x(t) - y(t)\|$$

Hence $\|Px - Py\|_X \leq L \cdot \delta \|x - y\|_X$

$$\leq \rho \|x - y\|_X$$

if $\delta \leq \frac{\rho}{L}$

Then choosing $\rho < 1$, and

$$\delta \leq \min \left(t_1 - t_0, \frac{Lr + \rho}{L}, \frac{L}{\rho} \right)$$

ensures that $P: S \rightarrow S$ is a contraction

mapping.

Hence, by the Theorem of Banach

there is a unique fixed point for P in S , the solution to the integral

equation. We can actually show that this is the only solution in X .

Since $x_0 \in B(x_0, r)$, any (continuous) solution $x(t)$ must ~~be~~ lie inside $B(x_0, r)$

parabola

for some interval of time. Suppose $x(t)$ leaves $B(x_0, r)$ and $t_0 + \mu$ is the first instant of time that $x(t)$ intersects $\partial B(x_0, r)$ the boundary of $B(x_0, r)$. Then

$$\|x(t_0 + \mu) - x_0\| = r.$$

On the other hand, $\forall t \leq t_0 + \mu$,

$$\|x(t) - x_0\| \leq \int_{t_0}^t (Lr + h) ds \quad (\text{see obs(1)})$$

so that $r = \|x(t_0 + \mu) - x_0\|$

$$\leq (Lr + h)\mu \Rightarrow \mu \geq \frac{r}{Lr + h}.$$

Hence the solution starting at x_0 stays in $B(x_0, r)$ and hence in S during $[t_0, t_0 + \mu]$.

Consequently uniqueness of solution in S

\Rightarrow uniqueness in X . \square

Here Back iteration = Picard-Lindelöf iteration

Notice that the map P in the

local existence and uniqueness theorem depends on x_0 in a continuous way.

(Corollary) Let (H) be a metric space that parameterizes

a family of differential equations and initial

conditions. Suppose parameterization is such

that the conditions of Theorem 2 are

satisfied. Then by Theorem 2 the solutions

obtained in Theorem 3 depends continuously on x_0 and more generally $\theta \in \mathbb{R}$. ■

Corollary 4 is a very useful result to keep in mind. The following lemma leads to comparison of solutions

Grönwall-Bollman Inequality / Lemma 5

Let $x: [a, b] \rightarrow \mathbb{R}$ be continuous and $y: [a, b] \rightarrow \mathbb{R}$ be continuous and non-negative. If a continuous function $y: [a, b] \rightarrow \mathbb{R}$ satisfies

$$y(t) \leq \lambda(t) + \int_t^a \mu(s)y(s)ds, \quad a \leq t \leq b,$$

then

$$y(t) \leq \lambda(t) + \int_t^a \mu(s)\lambda(s) \exp\left[\int_t^s \mu(r)dr\right] ds, \quad a \leq t \leq b.$$

In particular if $\lambda(t) \equiv \lambda$ is a constant, then

$$y(t) \leq \lambda \exp\left[\int_t^a \mu(r)dr\right].$$

If in addition, $\mu(t) \equiv \mu \geq 0$ is a constant, then

$$y(t) \leq \lambda \exp[\mu(t-a)].$$

Proof: Let $z(t) = \int_t^a \mu(s)y(s)ds$ and

$$v(t) = z(t) + \lambda(t) - y(t) \geq 0.$$

Then, z is differentiable and

$$z'(t) = \mu(t)y(t)$$

$$= \mu(t)z(t) + \mu(t)\lambda(t) - \mu(t)v(t).$$

Then z solves equation $z'(t) = \mu(t)z(t) + \mu(t)\lambda(t) - \mu(t)v(t)$. (since $z(0) = 0$)

$$z'(t) = \int_t^a \mu(s)\phi'(t,s) [\mu(s)\lambda(s) - \mu(s)v(s)] ds$$

where $\phi(t, s) = \exp \left[\int_t^s \mu(r) dr \right] > 0$
 By hypothesis, $\int_t^a \phi(t, s) \mu(s) r(s) ds \geq 0$. Therefore,

$$z(t) \leq \int_t^a \exp \left(\int_t^s \mu(r) dr \right) \cdot \lambda(s) \mu(s) ds$$

and, since $y(t) \leq \lambda(t) + z(t)$, the proof

of the general case is completed.

The remaining cases amount to

computing integrals — left to the reader. ■

Corollary 6 $f(t, x)$ is piecewise continuous in t and

Lipschitz in x on $[t_0, t_1] \times W$ with
 Lipschitz constant L , where $W \subset \mathbb{R}^n$ is an
 open connected set. Let $y(t)$ and $z(t)$
 be solutions of

$$y' = f(t, y); \quad y(t_0) = y_0$$

and $z' = f(t, z) + g(t, z); \quad z(t_0) = z_0$

such that $y(t), z(t) \in W \forall t \in [t_0, t_1]$.

Suppose

$\|g(t, x)\| \leq \mu$ $\forall (t, x) \in [t_0, t_1] \times W$
 for some $\mu \geq 0$, and $\|y_0 - z_0\| \leq \epsilon$.

Then,

$$\|y(t) - z(t)\| \leq \epsilon \exp \left[L(t - t_0) \right] + \frac{\mu}{L} \{ \epsilon - 1 \}$$

$\forall t \in [t_0, t_1]$

In these applications it is the original inequality - Bellman inequality, one in turning an implicit inequality explicit - in effect "solving the inequality".

$$= \gamma e^{L \cdot (t-t_0)} + \frac{\gamma}{L} (e^{L \cdot (t-t_0)} - 1)$$

(Integration by parts)

$$= \gamma + \mu \cdot (t-t_0) + \gamma - \mu \cdot (t-t_0) + \gamma \cdot e^{L \cdot (t-t_0)} + \int_{t_0}^t \mu \cdot e^{L \cdot (t-s)} ds$$

$$\|y(t) - z(t)\| \leq \gamma + \mu \cdot (t-t_0) + \int_{t_0}^t L \cdot (\gamma + \mu(s-t_0)) \cdot e^{L \cdot (t-s)} ds$$

By the Gronwall-Bellman inequality,

$$\leq \gamma + \mu \cdot (t-t_0) + \int_{t_0}^t L \|y(s) - z(s)\| ds$$

$$+ \int_{t_0}^t \|g(s, z(s))\| ds$$

$$\|y(t) - z(t)\| \leq \|y_0 - z_0\| + \int_{t_0}^t \|f(s, y(s)) - f(s, z(s))\| ds$$

Then,

$$z(t) = z_0 + \int_{t_0}^t [f(s, y(s)) + g(s, z(s))] ds$$

$$\text{Proof: } y(t) = y_0 + \int_{t_0}^t f(s, y(s)) ds$$

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Remark

Corollary 6 allows us to qualitatively estimate the effects of perturbation - in initial condition and the dynamics. Such estimates are useful to keep in mind - all models of physical systems display errors due to various unavoidable approximations.

Theorem 7 (Global Existence and Uniqueness)

Suppose $f(t, x)$ in Theorem 3 is piecewise continuous in t , and satisfies

$$\|f(t, x_0)\| \leq h$$

$$\text{global Lipschitz} \rightarrow \|f(t, x) - f(t, y)\| \leq L \cdot \|x - y\|$$

then the o.d.e. $x(t) = f(t, x)$ (with $x(t_0) = x_0$) has a unique solution on $[t_0, t_1]$.

Proof: We show how to modify the proof of Theorem 3. There we now let r be arbitrarily large (due to the global Lipschitz condition) so that $\frac{Lr+h}{r} > \frac{L}{\rho}$.

(by taking $r > \frac{\rho(L+h)}{\rho-L}$) Thus we only need $\delta \leq \min\{t_1 - t_0, \frac{L}{\rho}\}$ for $\rho > 1$. If $t_1 - t_0 \leq \frac{L}{\rho}$, we could let $\delta = t_1 - t_0$ and we are done.

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If not, choose $\delta = \frac{L}{f}$, divide $[t_0, t_1]$ into finite number L of subintervals of length $\delta = \frac{L}{f}$ and repeat that many times the arguments of Theorem 3. This completes the proof.

EXAMPLE

$$\dot{x} = -x^3$$

does not satisfy a global Lipschitz condition. But there is a unique solution

$$x(t) = \text{sgn}(x_0) \sqrt[3]{x_0^2 - 2x_0^2 \cdot (t-t_0)}$$

$t \geq t_0$

through $x(t_0) = x_0$.

The essential idea here is that

if $x(t_0) = a$, the set $\{x : |x| \leq a\}$

is a positively invariant closed and bounded

solution set for the dynamics $\dot{x} = -x^3$.

This idea can be generalized to

Theorem

$f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is locally Lipschitz on

a domain $D \subset \mathbb{R}^n$. Suppose there is

a closed and bounded set $W \subset D$ such

that $x(t_0) = x_0 \in D$ and flow points

into W . Then there is a unique solution

$x(t)$ of $\dot{x} = f(x)$ such that $x(t_0) = x_0$

Proof: EXERCISE.

Some Definition and Properties Pertaining to Lipschitz Condition.

Defⁿ (a) f is locally Lipschitz on a domain $D \subset \mathbb{R}^n$ if each point p of D has neighborhood

(i.e. ball $B_\epsilon(p)$ surrounding $p, \epsilon > 0$) such that

$$\|f(x) - f(y)\| \leq L_\epsilon \|x - y\| \quad \forall x, y \in B_\epsilon$$

Defⁿ (b) f is Lipschitz on a set W if

$$\|f(x) - f(y)\| \leq L \|x - y\|, \quad \forall x, y \in W.$$

Properties

(a) f is locally Lipschitz on a domain $D \Rightarrow f$ is continuous on D .

(b) f is Lipschitz on domain $D \Rightarrow f$ is uniformly continuous on D .

(c) converse of (b) is not true:

Consider $f(x) = x^2$ on $(-1, 1)$

(d) f is locally Lipschitz on domain $D \Rightarrow f$ is Lipschitz on D (due to lack of uniformity of the Lipschitz constant)

(e) f is locally Lipschitz on domain $D \Rightarrow$ Lipschitz on every closed and bounded subset of D .

(f) f is continuously differentiable $\Rightarrow f$ is locally Lipschitz. Converse is far from true.